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Integrated monitoring of a slowly moving deep-seated gravitational slope deformation based on multitemporal terrestrial laser scanning and total station measurements preliminary results of the **OPERANDUM project** 

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## Abstract

Deep-seated gravitational slope deformations (DSGSDs) In the present study the displacement of an active sub-systain slopes continuously reshaping surface topography. derstand their spatio-temporal activity, main causes and monitoring techniques are employed to assess the movement of DSGSDs at points, along profile lines or area-wide. ons, mainly regarding the spatio-temporal resolution and measurements), area-wide data acquisition techniques deto provide independent results for validation purposes.

are slowly moving mass-movement phenomena on moun- tem of a DSGSD located in Vögelsberg (Tyrol, Austria) is monitored by means of multi-temporal terrestrial laser scan-Their permanent monitoring is an important task to un- ning (TLS) and an automated tracking total station (ATTS). The currently active part of the DSGSD covering about 0.25 drivers and to prevent potential impacts. Currently, various km<sup>2</sup> in the lower part of the hillslope shows generally enhanced movements. Phases of acceleration and deceleration are clearly noticeable on parts of the slope and can be Each technique comes along with advantages and limitati- related with pore pressures measured in two groundwater wells. However, the precise continuous monitoring using coverage. While measurements at points or along lines the ATTS provides data for selected points (retroreflecting typically feature a high temporal resolution (i.e. continuous prisms) and does not readily allow an area-wide interpretation of the deformation pattern. Therefore, the analyses pend on the scope and budget of a study (e.g. frequency based on the temporally sparse but spatially distributed of laser scanning campaigns). Therefore, many monitoring TLS time series can be used to overcome this limitation. In projects rely on two or more data acquisition techniques for this regard, the advantages of both, the ATTS and the TLS exploiting their synergies, to overcome their limitations and monitoring can be exploited to deepen the understanding of the DSGSD.

Both monitoring campaigns started in troduced. After the fine registration based tive area are clearly discernible from the mid-2016 and are still ongoing. The time on the iterative closest point algorithm, area around it. The laser scanning results period considered in the present study point-to-plane distances to a selected re- for the same buildings show a distriburanges from 2016/06 to 2019/11, in- ference TLS point cloud were computed, tion comparable to the ATTS results, but cluding 13 TLS acquisition campaigns. revealing an uncertainty of 6.5 cm (95% cannot be as clearly discerned from the Two long-range terrestrial laser scanners quantile) considered as detection limit surrounding area. This is certainly rela-(Riegl VZ-4000 and Riegl VZ-6000) have for landslide-induced displacements and ted to the higher positional uncertainty been used to acquire 3D point clouds from deformation. The ATTS conducts hourly of the TLS point clouds. However, displaat least three scanning positions located measurements of the position of 53 re- cements of more than 5 cm can be deon the opposite side of the valley, covering troreflecting prisms installed on buildings tected. In case of slowly moving DSGSDs a range between 600 and 2500 m. From (n=46) and poles (n=6) within the active this means that a sufficient time span is an additional scanning position above the area and surrounding it. The ATTS has necessary until this detection limit is surnorthern scarp of the active area scan- been installed on the opposite side of the passed. Further work will focus on the exning was only possible using the Riegl VZ- valley with measurement distances bet- ploitation of all acquired TLS point clouds 4000 due to eye safety restrictions of the ween 600 and 1700 m. The total station's for reconstructing area-wide displace-Riegl VZ-6000. The accuracy of the used measurement accuracy has been asses- ment time series. Furthermore, the dislaser scanners depends on several para- sed based on the measurement time se- placement of other above-ground objects meters including sensor characteristics ries of 17 retroreflecting prisms on stable such as trees or poles will be evaluated to (e.g. the beam divergence), measurement grounds with a total displacement less explore the spatial displacement pattern range, incidence angle, surface roughness than 1 cm (on average less than 0.3 cm/ in more detail. and atmospheric conditions. Except for year). The analysis revealed an uncertainthe latter which is still difficult to consider ty less than 0.4 cm (95% guantile), also The present study was conducted within in long-range TLS studies, these effects depending on the measurement range. have been included during the proces-

sing of the point clouds, quantifying the Comparing the preliminary results of resulting uncertainty for each point. The both monitoring techniques considering novation programme under grant agreeregistration of the point clouds was done the buildings in the active and surroun- ment No 776848. based on extracted roofs and walls of sta- ding area, the magnitudes of the derived ble buildings identified in the ATTS time 3D displacement vectors for the period series. For the sampling of suitable buil- 2016/06 to 2019/11 are in general agding facets thresholds for the computed reement (see boxplots in Figure 3). Paruncertainty, the planarity and the devia- ticularly in case of the ATTS results the tion of locally fitted planes have been in- displacements of buildings within the ac-

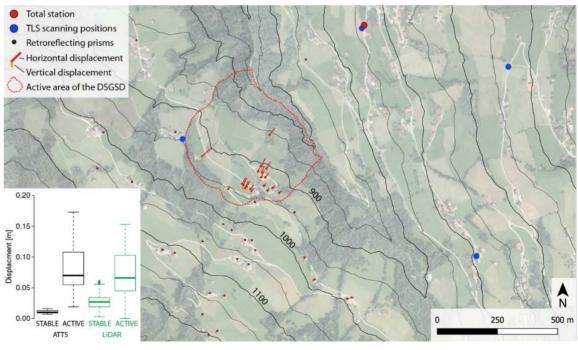


Figure 3: Monitoring setup and preliminary results of the displacement monitoring considering the period between 2016/06 and 2019/11.



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